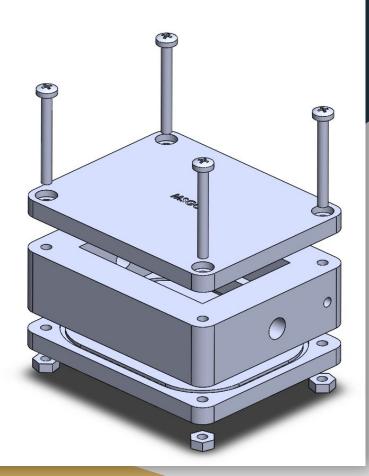
The Waterproof Cutdown, V3

Tim Uhlenbruck, Isaac Schmidt, and Lance Nichols

Development of the Box

- Challenges
- Design choices
- Materials



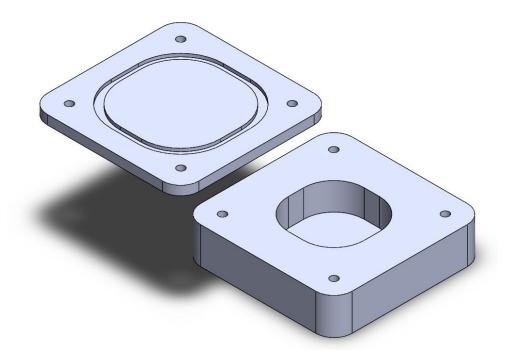
The String

- How?
- Compression fittings
- Silicone Seal
- BIG Needle



3D Printed Box

- Can it be done
- What material
- Testing



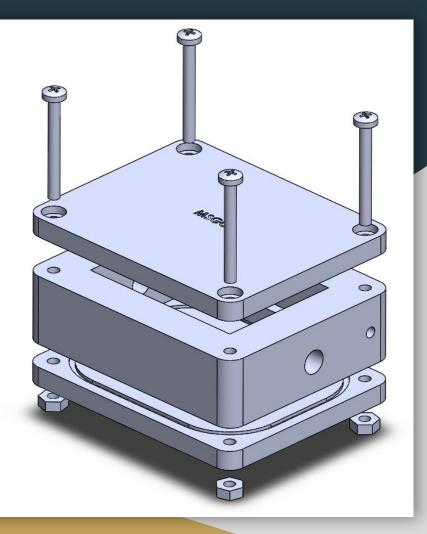
Tapping a 3D Print

- Will it work
- Will it be waterproof



Final Design

- Opens from both sides
- Waterproof
- String though both sides
- Seat Belt
- O-Ring choice



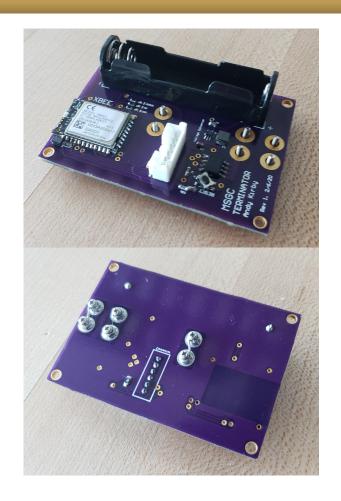
Final Manufacturing

- 3D printed in ABS
- Silicone seals cut with sharpened metal pipe
- Nylon screws



Hardware Overhaul And Specialization

- XBEE 3
- Smaller BOM
- Onboard MOSFET
- Board Mounted Nichrome



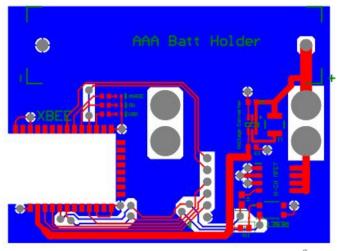
New Operating Voltage

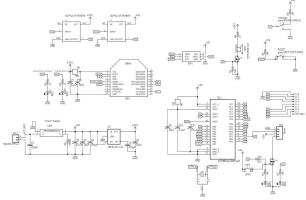
- XBEE 3 3.3v
- AAA battery 1.5v



Microcontroller and Radio Integration

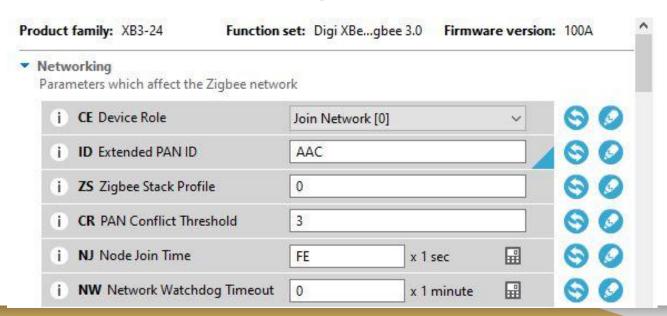
Simpler Overall Hardware





XCTU

"Commands" (settings)



API Configuration

Change API mode configuration

i AP API Enable	MicroPython REPL [4]		v	4	0	1
i AO API Output Mode	0	Bitfield		Ì	0	9
i AZ Extended API Options	0	Bitfield			9	0

▼ UART Interface

Configuration options for UART

i BD UART Baud Rate	115200 [7]	v	0	0
i NB UART Parity	No Parity [0]	~	9	0
i SB UART Stop Bits	One stop bit [0]	~	9	9
i RO Transparent Pation Timeout	3 x character times		9	9

XBEE 3 and MicroPython

No more flashing--Interpreter



```
COM4 - 115200/8/N/1/N ▼ 5
                                                                                ■ Cutdown3PycharmProject ▼
🚜 main.py
      print('ID: ' + str(xbee.atcmd('MY')))
      # PIN DEFINITIONS
      USER_LED = Pin(machine.Pin.board.D4, Pin.OUT, value=0)
      PRI_MOSFET = Pin(machine.Pin.board.D12, Pin.OUT, value=0)
      ASSOC_LED = Pin(machine.Pin.board.D5, Pin.OUT, value=0)
      # FLAG DEFINITONS
      priCutdownFlag = True
      secCutdownFlag = True
      while True:
          packet = xbee.receive()
          #print(packet)
          if packet != None:
              print(packet.get('payload'))
              check_for_command(packet.get('payload'))
          USER_LED.value(1)
          time.sleep(0.2)
          USER_LED.value(0)
          time.sleep(0.2)
```

Questions?